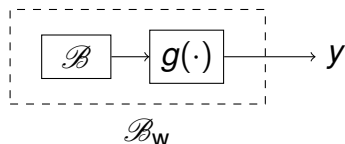


Identification of autonomous Wiener systems

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Consider the familiar Wiener system,
however, without an input signal



\mathcal{B} — autonomous linear time-invariant subsystem

g — static nonlinear subsystem

\mathcal{B}_W — autonomous Wiener system

The response y is due to initial conditions

existing methods assume zero initial conditions

main result: $\mathcal{B}_w \subseteq$ LTI system (of high order)

this result suggest an identification method

Parameterization of the model

order- n linear subsystem

$$\mathcal{B} = \mathcal{B}(\lambda) := \left\{ z \in \mathbb{R}^N \mid z = \sum_{i=1}^n \alpha_i \exp_{\lambda_i}, \alpha \in \mathbb{C}^n \right\} \quad (1)$$

degree- d static nonlinear subsystem

$$y = g(z) := \theta^\top v(z), \quad \text{where} \quad v(z) = \begin{bmatrix} z^0 \\ z^1 \\ \vdots \\ z^d \end{bmatrix} \quad (2)$$

autonomous Wiener system

$$\mathcal{B}(\lambda, \theta) := \left\{ y \in \mathbb{R}^N \mid (1,2) \text{ hold for } \alpha \in \mathbb{C}^n \right\}$$

Main result: $\mathcal{B}(\lambda, \theta)$ is included in an autonomous linear time-invariant system

there is λ_w , such that

$$\mathcal{B}(\lambda, \theta) \subseteq \mathcal{B}(\lambda_w)$$

the order of the embedding system $\mathcal{B}(\lambda_w)$ is

$$n_w = \binom{n+d}{d} = \frac{(n+1)(n+2)\cdots(n+d)}{d!}$$

its eigenvalues λ_w are products of d elements of $1 \cup \lambda$

$$\lambda_{w,i} = \prod_{j=1}^d \lambda_{k_{i,j}}, \quad \text{where, } \lambda_0 := 1, \quad k_{i,j} \in \{0, 1, \dots, n\}$$

Strategy: compare the outputs of $\mathcal{B}(\lambda_w)$ and $\mathcal{B}(\lambda, \theta)$

the output of $\mathcal{B}(\lambda_w)$ is sum-of-damped-exponentials

$$y = \beta_1 \exp_{\lambda_{w,1}} + \cdots + \beta_{n_w} \exp_{\lambda_{w,n_w}}, \quad \beta \in \mathbb{R}^{n_w}$$

consider a general basis element

$$v_j(z(t)) = (z(t))^j = \left(\sum_{i=1}^n \alpha_i \lambda_i^t \right)^j$$

v_j is a sum-of-damped-exponentials

$$v_j(z(t)) = \sum_{i=1}^{n_j} \gamma_i \mu_{i,j}^t, \quad \text{where } \mu_{i,j}^t = \prod_{\ell=1}^j \lambda_{k_{i,j,\ell}}$$

then, the output

$$y(t) = g(z(t)) = \theta v(z(t))$$

is also a sum-of-damped-exponentials

$$y(t) = \sum_{i=1}^{n_w} \zeta_i \lambda_{w,i}^t, \quad \text{where } \lambda_w = \bigcup_{j=0}^d \bigcup_{i=0}^j \mu_{i,j}$$

$\lambda_w =$ all products of d elements of $1 \cup \lambda(\mathcal{B})$

however, $\zeta \in$ subset of $\mathbb{R}^{n_w} \implies \mathcal{B}(\lambda, \theta) \subseteq \mathcal{B}(\lambda_w)$

Corollary: link between λ_w and λ

the symmetric, rank-1, d -way tensor

$$T := \lambda \times_1 \lambda \times_2 \cdots \times_{d-1} \lambda$$

has as unique elements $\lambda_{w,1}, \dots, \lambda_{w,n_w}$

Identification problem

given: monomial basis v and a finite trajectory

$$y_d = (y_d(1), \dots, y_d(T))$$

of an autonomous Wiener system $\mathcal{B}(\lambda, \theta)$

find: the order n and parameters $\hat{\lambda}, \hat{\theta}$, such that

$$\mathcal{B}(\lambda, \theta) = \mathcal{B}(\hat{\lambda}, \hat{\theta})$$

Procedure for identification of autonomous Wiener system

1. identify \mathcal{B}_w from the given output data
2. compute the linear subsystem \mathcal{B} from \mathcal{B}_w
3. compute the nonlinear subsystem g from \mathcal{B}_w and \mathcal{B}

1) identification of \mathcal{B}_w from y

minimal number of samples needed: $T_{\min} = 2n_w + 1$

can be collected from n_w experiments with $n_w + 1$ samples

issue: \mathcal{B}_w is a stiff system

2) computation of \mathcal{B} from \mathcal{B}_w

rank-1 factorization of symmetric, d -way tensor

$$T(\lambda(\mathcal{B}_w)) = \lambda \times_1 \lambda \times_2 \cdots \times_{d-1} \lambda$$

issue: order of the eigenvalues $\lambda(\mathcal{B}_w)$

the combinatorial number of factorizations can be avoided

3) computation of g from \mathcal{B}_w and \mathcal{B}

simultaneous rank-1 factorization of d tensors

this is a structured data fusion problem

if g has first order term, there is a simple solution