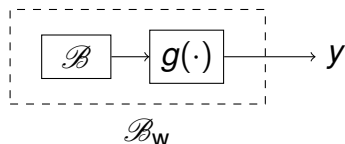


# Identification of autonomous Wiener systems

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Consider the familiar Wiener system,  
however, without an input signal



$\mathcal{B}$  — autonomous linear time-invariant subsystem

$g$  — static nonlinear subsystem

$\mathcal{B}_W$  — autonomous Wiener system

# The response $y$ is due to initial conditions

existing methods assume zero initial conditions

main result:  $\mathcal{B}_w \subseteq$  LTI system (of high order)

this result suggest an identification method

# Parameterization of the model

order- $n$  linear subsystem

$$\mathcal{B} = \mathcal{B}(\lambda) := \left\{ z \in \mathbb{R}^N \mid z = \sum_{i=1}^n \alpha_i \exp_{\lambda_i}, \alpha \in \mathbb{C}^n \right\} \quad (1)$$

degree- $d$  static nonlinear subsystem

$$y = g(z) := \theta^\top v(z), \quad \text{where} \quad v(z) = \begin{bmatrix} z^0 \\ z^1 \\ \vdots \\ z^d \end{bmatrix} \quad (2)$$

autonomous Wiener system

$$\mathcal{B}(\lambda, \theta) := \left\{ y \in \mathbb{R}^N \mid (1,2) \text{ hold for } \alpha \in \mathbb{C}^n \right\}$$

# Main result: $\mathcal{B}(\lambda, \theta)$ is included in an autonomous linear time-invariant system

there is  $\lambda_w$ , such that

$$\mathcal{B}(\lambda, \theta) \subseteq \mathcal{B}(\lambda_w)$$

the order of the embedding system  $\mathcal{B}(\lambda_w)$  is

$$n_w = \binom{n+d}{d} = \frac{(n+1)(n+2)\cdots(n+d)}{d!}$$

its eigenvalues  $\lambda_w$  are products of  $d$  elements of  $1 \cup \lambda$

$$\lambda_{w,i} = \prod_{j=1}^d \lambda_{k_{i,j}}, \quad \text{where, } \lambda_0 := 1, \quad k_{i,j} \in \{0, 1, \dots, n\}$$

# Strategy: compare the outputs of $\mathcal{B}(\lambda_w)$ and $\mathcal{B}(\lambda, \theta)$

the output of  $\mathcal{B}(\lambda_w)$  is sum-of-damped-exponentials

$$y = \beta_1 \exp_{\lambda_{w,1}} + \cdots + \beta_{n_w} \exp_{\lambda_{w,n_w}}, \quad \beta \in \mathbb{R}^{n_w}$$

consider a general basis element

$$v_j(z(t)) = (z(t))^j = \left( \sum_{i=1}^n \alpha_i \lambda_i^t \right)^j$$

$v_j$  is a sum-of-damped-exponentials

$$v_j(z(t)) = \sum_{i=1}^{n_j} \gamma_i \mu_{i,j}^t, \quad \text{where } \mu_{i,j}^t = \prod_{\ell=1}^j \lambda_{k_{i,j,\ell}}$$

then, the output

$$y(t) = g(z(t)) = \theta v(z(t))$$

is also a sum-of-damped-exponentials

$$y(t) = \sum_{i=1}^{n_w} \zeta_i \lambda_{w,i}^t, \quad \text{where } \lambda_w = \bigcup_{j=0}^d \bigcup_{i=0}^j \mu_{i,j}$$

$\lambda_w =$  all products of  $d$  elements of  $1 \cup \lambda(\mathcal{B})$

however,  $\zeta \in$  subset of  $\mathbb{R}^{n_w} \implies \mathcal{B}(\lambda, \theta) \subseteq \mathcal{B}(\lambda_w)$

## Corollary: link between $\lambda_w$ and $\lambda$

the symmetric, rank-1,  $d$ -way tensor

$$T := \lambda \times_1 \lambda \times_2 \cdots \times_{d-1} \lambda$$

has as unique elements  $\lambda_{w,1}, \dots, \lambda_{w,n_w}$



# Identification problem

**given:** monomial basis  $v$  and a finite trajectory

$$y_d = (y_d(1), \dots, y_d(T))$$

of an autonomous Wiener system  $\mathcal{B}(\lambda, \theta)$

**find:** the order  $n$  and parameters  $\hat{\lambda}, \hat{\theta}$ , such that

$$\mathcal{B}(\lambda, \theta) = \mathcal{B}(\hat{\lambda}, \hat{\theta})$$

# Procedure for identification of autonomous Wiener system

1. identify  $\mathcal{B}_w$  from the given output data
2. compute the linear subsystem  $\mathcal{B}$  from  $\mathcal{B}_w$
3. compute the nonlinear subsystem  $g$  from  $\mathcal{B}_w$  and  $\mathcal{B}$

# 1) identification of $\mathcal{B}_w$ from $y$

minimal number of samples needed:  $T_{\min} = 2n_w + 1$

can be collected from  $n_w$  experiments with  $n_w + 1$  samples

issue:  $\mathcal{B}_w$  is a stiff system

## 2) computation of $\mathcal{B}$ from $\mathcal{B}_w$

rank-1 factorization of symmetric,  $d$ -way tensor

$$T(\lambda(\mathcal{B}_w)) = \lambda \times_1 \lambda \times_2 \cdots \times_{d-1} \lambda$$

issue: order of the eigenvalues  $\lambda(\mathcal{B}_w)$

the combinatorial number of factorizations can be avoided

### 3) computation of $g$ from $\mathcal{B}_w$ and $\mathcal{B}$

simultaneous rank-1 factorization of  $d$  tensors

this is a structured data fusion problem

if  $g$  has first order term, there is a simple solution